Assessment of downy mildew in grapevine using computer vision and fuzzy logic. Development and validation of a new method

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ABSTRACT

Downy mildew is a major disease of grapevine. Conventional methods for assessing crop diseases are time-consuming and require trained personnel. This work aimed to develop and validate a new method to automatically estimate the severity of downy mildew in grapevine leaves using fuzzy logic and computer vision techniques. Leaf discs of two grapevine varieties were inoculated with Plasmopara viticola and subsequently, RGB images were acquired under indoor conditions. Computer vision techniques were applied for leaf disc location in Petri dishes, image pre-processing and segmentation of pre-processed disc images to separate the pixels representing downy mildew sporulation from the rest of the leaf. Fuzzy logic was applied to improve the segmentation of disc images, rating pixels with a degree of infection according to the intensity of sporulation. To validate the new method, the downy mildew severity was visually evaluated by eleven experts and averaged score was used as the reference value. A coefficient of determination (R²) of 0.87 and a root mean squared error (RMSE) of 7.61 % was observed between the downy mildew severity obtained by the new method and the visual assessment values. Classification of the severity of the infection into three levels was also attempted, achieving an accuracy of 86 % and an F1 score of 0.78. These results indicate that computer vision and fuzzy logic can be used to automatically estimate the severity of downy mildew in grapevine leaves. A new method has been developed and validated to assess the severity of downy mildew in grapevine. The new method can be adapted to assess the severity of other diseases and crops in agriculture.

KEYWORDS: non-invasive sensing technologies, plant disease detection, Plasmopara viticola, precision viticulture.
INTRODUCTION

Grapevine is globally considered one of the most important crops for its economic relevance (Buonassisi et al., 2017). The occurrence of diseases caused by fungi, bacteria and viruses is the cause of severe economic losses due to the reduced quantity and quality of production. Among grapevine diseases, downy mildew is considered of primary importance (Buonassisi et al., 2017) due to the significant yield losses that it causes and the costs of the protection measures. Downy mildew is caused by the biotrophic oomycete *Plasmopara viticola*, an obligate parasite of grapevine. Under favourable weather conditions, the pathogen can infect all leaves and bunches of the plant if it is not adequately controlled (Toffolatti et al., 2018). As a result, grapevine downy mildew has become a pressing issue that has deserved attention worldwide.

The assessment of plant disease can be expressed in terms of incidence, i.e., the proportion of the plant units that are diseased in a defined population or sample (Madden et al., 2017), or severity, which is the proportion of the plant exhibiting visible disease symptoms or sporulation, usually expressed as a percentage (Madden et al., 2017). To perform the disease evaluation, personnel with appropriate competence and expertise must be selected (Mokhtar et al., 2015). The traditional phenotyping techniques, in fact, rely on visual ratings of the disease symptoms in grapevine leaves and bunches or the sporulation extent in experimentally inoculated leaves. More precisely, visual estimation is carried out by assigning a value to the severity of symptoms or sporulation perceived by the human eye. It requires a considerable time and can be subjective, i.e., influenced by the operator’s ability to discriminate the disease symptoms/pathogen sporulation and associated with errors (Bock et al., 2010). The application of new sensing technologies gives the opportunity to remove the inconsistencies linked to the operator-based visual assessment and to improve the speed, accuracy, reproducibility and versatility of the disease assessment in several crops (Bock et al., 2020).

The application of new and emerging technologies has allowed the development of automatic and semi-automatic methods for plant disease assessment. Visualisation of the plant infections at different symptomatic stages can be achieved using several sensing technologies such as computer vision (Barbedo, 2013, 2014), hyperspectral imaging (Lowe et al., 2017), thermography (Stoll et al., 2008) and chlorophyll fluorescence (Cséfalvay et al., 2009). Methods based on the chlorophyll fluorescence, hyperspectral, and thermal images require expensive equipment and sophisticated analysis methods. In contrast, computer vision can be applied to RGB images that can be acquired using a large number of very accessible, economically-friendly devices (Lin et al., 2019).

Several reports have shown the usefulness of image analysis for the objective assessment of disease severity in different plant–pathogen interactions, including grapevine (Barbedo, 2014; Barbedo, 2018b; Bock et al., 2008; Boso et al., 2004; Corkidi et al., 2006; Stoll et al., 2008; Tucker et al., 2001; Wijekoon et al., 2008). Moreover, the assessment of disease severity throughout image analysis allows one to obtain high-throughput phenotyping data in a non-destructive and simple way and could offer new opportunities for a more precise evaluation of plant-pathogen interaction in leaf disc bioassays (Peressotti et al., 2011). Diseased visible symptoms can be assessed and distinguished from the infected area using computer vision techniques (Barbedo, 2013; Barbedo, 2014; Stewart and McDonald, 2014). Infected area segmentation has witnessed various algorithms, such as the segmentation of infected pixels based on grey levels (Price et al., 1993). Segmentation is used for partitioning the image to find regions of interest and it aims to separate the region having abnormalities. Images with disease spots on the leaves are considered and converted into a binary image separating background and leaf pixels. Leaf pixels are also divided into the diseased area and the rest of the leaf. Once the total disease area and total leaf area are known, the severity of the disease is estimated by calculating the percentage of the infected region (number of diseased pixels) over the entire leaf region (Mukherjee, 2020). All image analysis studies reported in the literature that are based on automatic or semi-automatic methods for the assessment of the disease severity have in common that digital evaluation is performed by detecting pixels with special features that define each particular disease symptom (Bock et al., 2010; Bock et al., 2020).

Image segmentation is one of the most utilised techniques to classify the infected area from the entire plant organ region. Grey levels and histograms of intensities have been used for image segmentation (Barbedo, 2014; Camargo and Smith, 2009). According to some works (Barbedo, 2013; Zhang et al., 2020), thresholding can be a useful tool for segmenting images, detecting disease symptoms and quantifying disease infection in plants.

Fuzzy logic can be combined with computer vision techniques to extract information that humans could perceive from regions of interest in images. Recently, this approach has been suggested to evaluate plant diseases (Mukherjee, 2020; Sibiya and Sumbwanymbe, 2019) and enhance image segmentation to locate diseased areas (Sekulska-Nalewajko and Goclawski, 2011). The application of a fuzzy threshold in segmentation has been suggested to improve disease quantification algorithms (Nagi and Tripathy, 2020; Nagi and Tripathy, 2021). These works pointed to the diversity of the use of fuzzy logic and the closeness of the results provided by the fuzzy logic to the expert’s evaluation.

The aim of this work was to develop and validate a new method to automatically assess the severity of downy mildew disease in grapevine leaves by combining fuzzy logic and computer vision techniques.

MATERIALS AND METHODS

For the evaluation of the severity of downy mildew disease in grapevine leaves under laboratory conditions, a new method was developed combining computer vision techniques with fuzzy logic. The process is summarised in Figure 1.
The first stage of the process was the preparation of the plant material and the RGB image acquisition. The second stage involved the use of computer vision techniques to find leaf discs in the image and to highlight the disease severity in each leaf disc. Finally, for validation, the downy mildew severity obtained from the sporulation located in each image was compared against the scores obtained by a visual assessment performed by experts.

1. Plant material and image acquisition

Leaf discs from grapevine plants were inoculated with a suspension of *Plasmopara viticola* sporangia and placed in Petri dishes with the abaxial side up. Leaf discs were imaged using a digital camera under laboratory conditions. Two different leaf grapevine data sets were used.

1.1. Set-1: Cabernet-Sauvignon

Plant preparation and image acquisition were carried out in April 2019 at the University of Milan (Milan, Italy). Fifty grapevine plants (cv. Cabernet-Sauvignon, *Vitis vinifera* L.) were grown in 5 L pots filled with commercial mixture peat (perlite and vermiculite) in a climate chamber at 23 ± 2 °C and 80 % relative air humidity. The photoperiod was 16 h of artificial light. During growth, plants were drip-watered regularly. Between one and three leaves (the third to the fifth leaf from the apex of the shoot) from each plant were excised, rinsed with distilled water and dried with filter paper. Leaf discs of 25 mm diameter were excised by a corkborer and placed in Petri dishes with the abaxial side up on wetted filter paper. Eight leaf discs were placed inside each Petri dish. Leaf discs were sprayed with 1 mL of a suspension of *P. viticola* sporangia (5 × 10^4 sporangia mL^-1) onto the abaxial leaf surface. The isolate of *P. viticola* was obtained from naturally infected plants maintaining the disease severity on grapevine leaves. Images were taken from 3 to 9 days after inoculation under laboratory conditions. A total of 14 Petri dishes and 109 leaf discs (between five and eight discs per dish) were imaged in this set.

1.1. Set-2: Tempranillo

Plant preparation and image acquisition occurred in November 2019 at the University of La Rioja (Logroño, Spain). Fifty grapevine plants (cv. Tempranillo, *Vitis vinifera* L.) were grown in 5 L pots filled with commercial mixture peat (perlite and vermiculite) in a climate chamber at 23 ± 2 °C and 80 % relative air humidity. The photoperiod was 16 h of artificial light. During growth, plants were watered regularly. Between one and three leaves from each plant were excised, rinsed with distilled water and dried with filter paper. Leaf discs of 15 mm diameter were excised with a corkborer and placed in Petri dishes with the abaxial side up on wetted filter paper. Nine leaf discs per placed in each Petri dish. Leaf discs were sprayed with 1 mL of a suspension of 5 × 10^4 sporangia mL^-1 onto the abaxial leaf surface. The isolate of *P. viticola* was obtained from naturally infected plants showing downy mildew symptoms. The Petri dishes with infected leaf discs were maintained in a humid chamber at 23 ± 2 °C for 9 days. RGB images with a resolution of 24 megapixels (6000 × 4000 pixels) were taken with a Sony alpha 7-II digital mirrorless camera (Sony Corp., Tokyo, Japan) with a Vario-Tessar FE 24–70 mm lens under indoor conditions. Images were taken from 4 to 9 days after inoculation under laboratory conditions. A total of 29 Petri dishes and 261 leaf discs (nine discs per dish) were imaged in this set.

2. Computer vision algorithm for downy mildew assessment

The new computer vision algorithm for assessing downy mildew in grapevine leaves consisted of four main steps: i) Leaf disc location in the Petri dishes, ii) image pre-processing iii) segmentation of pre-processed images to separate the pixels representing downy mildew infection from the rest and iv) estimation of downy mildew severity for each leaf disc.
2.1. Leaf disc location on Petri dishes

Each leaf disc of the Petri dishes was located using Hough’s transform (Yuen et al., 1990), obtaining the location of its centre on the image and its radius. This method segmented the discs ignoring the background and the Petri dish, regardless of potential differences in disc sizes.

To achieve this disc localisation, a preliminary step was required involving common colour correction (Figure 2). Likewise, the images belonging to Set-2 were adapted so that the approximate diameter of the discs was similar to those of Set-1 (from 400 pixels in diameter to 264 pixels), resizing the images in this set from 6000 × 4000 pixels to 3960 × 2640 pixels. Then, the colour space was changed from RGB to HLS to separate the colour (hue), lightness and saturation of each image and to use the saturation values to highlight the leaf discs from the rest of the image, avoiding the identification of the Petri dish due to its circular shape (Figure 2b). This HLS image was then smoothed with the median filter used in the initial stage of the mean shift segmentation (Comaniciu and Meer, 2002) and with the median blur filter to reduce image noise (Figure 2c). Finally, the saturation component of the blurred images was used for the localisation of the leaf discs with the Hough Transform from the OpenCV 4.5.1.48 library applying the Hough gradient method, with a minimum distance of 190 pixels between detected centres, an upper threshold of 100 for the internal Canny edge detector, a minimum radius to be detected of 115 pixels, a maximum radius to be detected of 145 pixels and an inverse ratio of the resolution of 1 (Figure 2d). Furthermore, the threshold for centre detection was automatically searched (varying the threshold between 11 and 25) to find eight circles in each image from Set-1 and nine circles in each image from Set-2.

In most cases, leaf discs were not represented by a perfect circle, so the Hough Transform had problems detecting the borders of the discs with full accuracy, as seen in Figure 2. To improve this detection, a radius reduction of 20 pixels was applied, discarding part of the background close to the borders that could be detected as part of the sporulation.

2.2. Image pre-processing

Image pre-processing was carried out to achieve the best possible differentiation between P. viticola sporulation and the rest of the leaf. Based on the images in the HLS colour space used for the disc location, the saturation channel of these images was selected to find the pixels that represented pathogen sporulation. Then, a median blur filter with a kernel of 3 × 3 pixels was used in the image that represented the saturation component to blur the image. Finally, Contrast Limited Adaptive Histogram Equalization (CLAHE; Pizer et al., 1987) was applied to improve the histogram contrast of all images, preventing some images from having significantly high or low lighting.

2.3. Segmentation of pre-processed images

To obtain a clear separation of the pixels corresponding to P. viticola sporulation and those representing the rest of the leaf, one independent image was prepared for each leaf disc (Figure 3a).

![FIGURE 2. Disc location steps: transforming the colour space from the original RGB (red, green and blue) image (a) to hue, lightness, saturation (HLS), applying the median filter of the mean shift segmentation (b), applying the median blur filter to the saturation component of the HLS colour space (c) and locating the discs using the Hough’s Transform (d). The located discs are highlighted with a green circumference (d).](image)

![FIGURE 3. Segmentation of a grapevine leaf disc. Original leaf disc (a), pre-processed image (grayscale) using the saturation component of hue, lightness, saturation (HLS) colour space (b), the segmentation obtained after applying the multi-threshold variant of the Otsu method (c) and histogram created with the saturation component and separated with segmentation (d). The separation of the red, blue and green regions (c) was made with the Otsu method.](image)
A pre-processed image of each leaf disc was obtained by the segmentation of each leaf disc with the same height and width as the disc diameter (Figure 3b).

Segmentation of pre-processed disc images was carried out using a threshold that separated the pixels between pathogen sporulation and the rest of the leaf in each disc (Figure 3c). Since leaves exhibited different saturation values, the multi-threshold variant of the Otsu method (Liao et al., 2001) was applied to leaf disc images to obtain a precise segmentation, which allowed several thresholds to be found to divide an image based on the histogram of the image (Figure 3d). For each image, three thresholds were found, which separated background pixels (previously labelled with the value zero to focus the analysis on the localised discs), P. viticola sporulation, light areas of the leaf and darker areas of the leaf (Figure 3). Considering that the second threshold separated the pathogen sporulation from the rest of the leaf, this threshold was used to select the most appropriate threshold for all discs.

A crisp threshold (Cui et al., 2010; Gutiérrez et al., 2021), dividing the pixels of the discs into disease infection and the rest of the leaf using a fixed value, was used. Furthermore, a fuzzy threshold based on Nagi and Tripathy (2020), assigning a degree of infection to the pixels depending on the value of the pixels using membership functions within a range, was also used due to the variability of saturation values that represent the sporulation. For this purpose, the distribution of the thresholds obtained from all the discs was used to select three representative threshold ranges: from the first quartile to the median (th1, between 92 and 103), from the first quartile to the third quartile (interquartile range, th2, between 92 and 119) and from the minimum to the third quartile (th3, between 58 and 119).

The degree of downy mildew infection was then evaluated by assigning a membership value to each pixel of the leaf disc image according to its saturation value. The membership value using the fuzzy threshold was calculated with some of the best-known membership functions in fuzzy logic (Robinson, 2003; Sambariya and Prasad, 2017; Warner et al., 2019): gaussian, S-shape, sigmoidal, trapezoidal and generalised bell. For each disc image, each pixel (p) was evaluated with one of the threshold ranges obtained with the Otsu method, according to the application of the membership function (Ross, 2005). Therefore, with fuzzy thresholding, the values of the pixels with infection vary between zero and one (the likelihood of a pixel corresponding to infection). In the case of crisp thresholding, the mask resulting from the thresholding represents the pixels with downy mildew infection as ones and the rest as zeros.

Due to the similarity between leaf nerves and sporulation saturation values, nerves were mistakenly detected as part of the infection. To reduce the negative impact of this detection, the shape of each region labelled as part of the infection was analysed on each disc to ignore areas that were similar to lines representing leaf nerves. Nerves were defined as regions with an eccentricity greater than 0.95 to exclude regions similar to circumferences; a minor axis length less than 20 pixels to account for shapes with a small width; and a major axis length greater than 5 pixels, to discard small regions. Besides, to give greater importance to the pixels detected as downy mildew infection, the morphological operation of dilation with a structuring element of a size of 5 × 5 pixels was applied (Figure 4), thus joining and enlarging small areas of pixels labelled as sporulation, which in the human eye would be detected as single areas, instead of separate areas that would result in much less severity.

![FIGURE 4](image)

**FIGURE 4.** Processing of infection mask extracted from the disc image (a). The infection mask represents its regions with different colours (b), lines detected as nerves (c) and the final mask ignoring nerves and applying dilation morphology transformation (d).

### 2.4. Downy mildew severity calculation

After obtaining a mask for each leaf disc (with the values of the pixels between 0 and 1), the sporulation was evaluated, and the severity was computed. Once the discs were located in each Petri dish image and the mask with the degree of infection of the pixels was obtained, the infection severity (s) in each disc was calculated considering the percentage of infection represented by the value of its pixels, according to the following equation:

\[
s = \frac{\sum_{i=0}^{n} v_i}{n} \times 100 \quad (10)
\]

where \( v_i \) represents the pixel value according to the degree of downy mildew infection detected by the membership function and \( n \) represents the total number of pixels assigned to the area of the disc which, depending on the radius obtained automatically by the Hough Transform, follows the equation \( n = \pi r^2 \).
3. Visual rating and validation

A visual rating of downy mildew severity was performed to validate the infection values yielded by the method developed using computer vision and fuzzy logic. Downy mildew severity in all leaf disc images was visually evaluated by eleven experts. Each panellist evaluated each leaf disc using a 0–100 scale (Bock et al., 2010), reflecting the percentage of downy mildew infection over the total leaf surface.

Prior to the visual evaluation of all leaf discs, the panellists were intensively trained. During the training, each panellist was provided with a downy mildew assessment scale composed of 20 leaf disc RGB images, covering a range of infection between 0 % and 100 %. Once the panellist got familiar with the scale, a training set of 36 leaf discs was provided together with a self-evaluation spreadsheet. Should the difference between the infection rating given by the panellist and that provided by the method differ more than 15 %, then re-training of the panellist was carried out. Only when the average difference between the panellist’s ratings and those yielded by the method was lower than 15 % then the panellist could start the evaluation of the leaf discs involved in the modelling.

During the visual inspection and rating of the leaf discs, each panellist assessed 370 leaf discs in two different sessions to avoid fatigue. To compare the infection ratings provided by the experts with those obtained by the new method, a value representative of all panellists was used. For this purpose, the evaluations of each disc were analysed using the interquartile range (IQR), the first quartile (Q1) and the third quartile (Q3) from the distribution of these evaluations to discard the extreme outliers (Chandola et al., 2009). Values outside the range between Q1 – (3IQR) and Q3 + (3IQR) were considered outliers. Once the extreme values of the evaluations were discarded, the average evaluation of each disc was considered as a representative value of the panellist visual rating.

The downy mildew severity values for each leaf disc obtained by the computer vision method were then compared with the average expert visual evaluation values (reference method). A simple linear regression model was applied to approximate the values obtained with the new method to the experts’ assessment. The determination coefficient (R2) and root mean square error (RMSE) were computed to compare the values obtained with the linear regression model and the expert assessment using 10-fold cross-validation.

Moreover, infection ratings were also analysed discretely, taking into account severity as levels (Nagi and Tripathy, 2020). To do this, different levels of infection severity were defined: low, including ratings between 0 and 25 %; middle, comprising severity values between 26 and 50 %; and high, including severity ratings between 51 and 100 %. Some examples of these assignments and the number of discs of each level available in each set can be seen in Table 1. The severity levels were compared using the accuracy, F1 score, recall and precision metrics. The definitions of these classification metrics are the following:

\[
\text{Accuracy} = \frac{T_x + T_m + T_h}{N} \quad (13)
\]

\[
\text{Precision} = \frac{TP}{TP + FP} \quad (14)
\]

\[
\text{Recall} = \frac{TP}{TP + FN} \quad (15)
\]

\[
F1 = 2 \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \quad (16)
\]

where \(T_x\) in accuracy metric reflects the number of discs correctly classified with level \(x\), representing \(x\) as \(L\) for the low level, \(M\) for the middle level and \(H\) for the high level, and \(N\) represents the number of discs evaluated. The last three metrics were used on each of the levels independently and their mean values were considered, with TP (true positives) being the number of hits for that level, FP (false positives) refers to the number of discs misclassified as that level, and FN (false negatives) corresponds to the number of discs misclassified as another level. A confusion matrix was also built to determine the number of discs correctly classified or designated as another level of severity.

### RESULTS AND DISCUSSION

The method developed provided information for each leaf disc in the Petri dish image (Figure 5), where the areas detected as infection (with blue values if the sporulation has a low intensity and pinker colours if the sporulation has a high intensity) and the percentage of infection calculated from the sporulation can be seen. This way, for each disc, the disease severity was evaluated through the evaluation of the level of downy mildew sporulation. Crisp thresholding (Figure 5b) detected the clearest pathogen sporulation. On the other hand, fuzzy thresholding also detected less clear sporulation, giving different values for areas of clear sporulation and areas of more intense sporulation when calculating severity (Figure 5c). Fuzzy logic allowed to provide an assessment of the severity of downy mildew close to the experts, treating regions with lower symptom intensity differently from others with higher symptom intensity. This is reflected in the visualisation of the symptoms (Figure 5c,f), where the mask representing the infection not only indicates the infected area but also provides visual information on the intensity of the symptoms in each part of the infected area. Apart from that, as seen in other works (Barbedo, 2014), when using pixel values to detect disease, it was necessary to discard leaf nerves that could be detected as having similar values to disease symptoms. This was achieved by the algorithm analysing the shape of the regions detected as sporulation, making these nerves minimally influential in the estimation of disease severity.

Comparing the evaluation of the discs calculated by the new method with the visual evaluation provided by eleven trained experts (summarised in Figure 6), a positive linear relationship was observed in all the cases, reaching an R2 value of 0.88 using a fuzzy threshold to segment all the discs (Figure 6e,f) and an R2 of 0.84 for individual sets (Figure 6a–d).
### TABLE 1. Examples of grapevine leaf discs showing downy mildew sporulation, severity level, percentage of downy mildew sporulation and number of leaf discs for each dataset.

<table>
<thead>
<tr>
<th>Grapevine leaf discs</th>
<th>Downy mildew severity level</th>
<th>Percentage of downy mildew sporulation (%)</th>
<th>Number of leaf discs</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Low</td>
<td>0–25</td>
<td>30</td>
</tr>
<tr>
<td></td>
<td>Middle</td>
<td>26–50</td>
<td>34</td>
</tr>
<tr>
<td></td>
<td>High</td>
<td>51–100</td>
<td>45</td>
</tr>
<tr>
<td></td>
<td>All</td>
<td>0–100</td>
<td>109</td>
</tr>
</tbody>
</table>

**FIGURE 5.** Original Petri dishes (a,d) with downy mildew estimation in each grapevine leaf disc using crisp (b,e) and fuzzy threshold (using the s-shape membership function) (c,f) in Set-1 (a–c) and Set-2 (d–f) were showed.
Despite the similarity of the results between the use of a crisp or fuzzy threshold, in all the graphs, it can be seen in Figure 6 that the evaluations calculated with the fuzzy threshold are more similar to the experts' evaluation. Although images from the two datasets presented differences in image capture, infection conditions and grapevine variety, the similar results from the same method in the two sets suggest that the developed method is consistent and robust against significant changes in image acquisition. This is also reflected in the comparison of the linear relationships using all the discs and those of each set individually, where using all the discs gives better results. Figure 6 also shows that the infection values provided by the method showed small differences with the experts' evaluation (mostly by slightly underestimating the disease incidence), so a linear regression was used to adapt them.

Adapting the severity estimation provided by the method to the experts' evaluation with linear regression, the proposed algorithm was evaluated using a 10-fold cross-validation, and the results are presented in Tables 2, 3 and 4, comparing severity values and levels. To see how P. viticola sporulation was best reflected by image saturation values, six types of thresholds and three ranges of saturation values were combined. Saturation ranges were estimated by applying the multi-threshold variant of the Otsu method to discs where sporulation differed from the rest of the leaf, considering the good performance of this method for separating the main areas of the images (Lin et al., 2019).

The results provided for both sets together (Table 2) indicate that the ranges chosen to separate sporulation from the rest of the leaf achieved a severity estimate similar to that provided by the

**FIGURE 6.** The linear relationship between downy mildew severity, evaluated using computer vision techniques, and expert visual assessment. Computer vision evaluations performed by crisp threshold (a,c,e) and fuzzy threshold using the s-shape membership function (b,d,f) in Set-1 (a,b), Set-2 (c,d) and both datasets jointly (e,f) are shown. The dashed lines indicate a perfect linear relationship and the continuous lines indicate the real linear relationship.
Experts, with a minimum $R^2$ value of 0.85 and a maximum RMSE value of 8.42 %, reaching an $R^2$ score of 0.87 and an RMSE of 7.61 % with a fuzzy threshold, using the s-shape membership function (in the range between the saturation value 92 and 103). The classification of leaf discs into three severity levels provided by the method and the carried out by the experts exhibited a good degree of coincidence, obtaining an accuracy of 86 %, an F1 score of 0.79, a precision of 0.83 and a recall of 0.76 with a fuzzy threshold, using the sigmoid membership function (in the range between the saturation value 58 and 119). The human evaluation of the level of infection in leaves can become a delicate work yielding very significant differences between assessments. This has been previously exposed by (Mukherjee, 2020), where fuzzy logic was used to achieve an appraisal that mimicked the subjectivity of the experts. The high accuracy values in the present work reflect the correct classification of most of the discs from the low level of infection, which has significantly more discs than the two other levels (as it can be shown in Table 1). This is particularly relevant as human inspection may disregard low levels of severity depending on the visual capability and acuity of each individual, which will not be overlooked by the method developed.

### Table 2

Regression (RMSE, $R^2$) and classification (accuracy, F1-score, precision, recall) results of the 10-fold cross-validation, comparing the expert visual assessment and the computer vision downy mildew estimation adapted with a linear regression model using different thresholds and membership functions in both datasets jointly. The value used for the crisp threshold is the mean of the range assigned to the threshold (th1: threshold 1; th2: threshold 2 and th3: threshold 3).

<table>
<thead>
<tr>
<th>Threshold Name</th>
<th>Range</th>
<th>Type</th>
<th>$R^2$</th>
<th>RMSE (%)</th>
<th>Accuracy</th>
<th>F1-score</th>
<th>Precision</th>
<th>Recall</th>
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<tr>
<td>th1</td>
<td>98</td>
<td>Crisp</td>
<td>0.87</td>
<td>7.62</td>
<td>0.86</td>
<td>0.77</td>
<td>0.79</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td>92–103</td>
<td>Gaussian</td>
<td>0.87</td>
<td>7.65</td>
<td>0.86</td>
<td>0.78</td>
<td>0.80</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td>92–103</td>
<td>S-shape</td>
<td>0.87</td>
<td>7.61</td>
<td>0.86</td>
<td>0.78</td>
<td>0.80</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td>92–103</td>
<td>Sigmoidal</td>
<td>0.87</td>
<td>7.66</td>
<td>0.86</td>
<td>0.78</td>
<td>0.80</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td>92–103</td>
<td>Trapezoidal</td>
<td>0.87</td>
<td>7.63</td>
<td>0.86</td>
<td>0.78</td>
<td>0.80</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td>92–103</td>
<td>Generalized Bell</td>
<td>0.87</td>
<td>7.65</td>
<td>0.86</td>
<td>0.78</td>
<td>0.80</td>
<td>0.76</td>
</tr>
</tbody>
</table>

### Table 3

Regression (RMSE, $R^2$) and classification (accuracy, F1-score, precision, recall) results, comparing the expert visual assessment and the computer vision estimation of downy mildew using the crisp and fuzzy threshold (th1: threshold 1 and th3: threshold 3) with the s-shape and the sigmoid membership functions in both datasets.

<table>
<thead>
<tr>
<th>Dataset</th>
<th>Threshold Name</th>
<th>Range</th>
<th>Type</th>
<th>$R^2$</th>
<th>RMSE (%)</th>
<th>Accuracy</th>
<th>F1-score</th>
<th>Precision</th>
<th>Recall</th>
</tr>
</thead>
<tbody>
<tr>
<td>Set-1</td>
<td>th1</td>
<td>98</td>
<td>Crisp</td>
<td>0.84</td>
<td>11.12</td>
<td>0.77</td>
<td>0.77</td>
<td>0.79</td>
<td>0.76</td>
</tr>
<tr>
<td></td>
<td></td>
<td>92–103</td>
<td>S-shape</td>
<td>0.84</td>
<td>11.05</td>
<td>0.79</td>
<td>0.79</td>
<td>0.80</td>
<td>0.78</td>
</tr>
<tr>
<td></td>
<td></td>
<td>89</td>
<td>Crisp</td>
<td>0.84</td>
<td>11.79</td>
<td>0.83</td>
<td>0.83</td>
<td>0.83</td>
<td>0.83</td>
</tr>
<tr>
<td></td>
<td></td>
<td>58–119</td>
<td>Sigmoidal</td>
<td>0.84</td>
<td>11.67</td>
<td>0.83</td>
<td>0.84</td>
<td>0.84</td>
<td>0.84</td>
</tr>
<tr>
<td>Set-2</td>
<td>th1</td>
<td>98</td>
<td>Crisp</td>
<td>0.84</td>
<td>5.54</td>
<td>0.89</td>
<td>0.52</td>
<td>0.55</td>
<td>0.51</td>
</tr>
<tr>
<td></td>
<td></td>
<td>92–103</td>
<td>S-shape</td>
<td>0.84</td>
<td>5.58</td>
<td>0.89</td>
<td>0.51</td>
<td>0.54</td>
<td>0.49</td>
</tr>
<tr>
<td></td>
<td></td>
<td>89</td>
<td>Crisp</td>
<td>0.76</td>
<td>6.51</td>
<td>0.88</td>
<td>0.50</td>
<td>0.52</td>
<td>0.48</td>
</tr>
<tr>
<td></td>
<td></td>
<td>58–119</td>
<td>Sigmoidal</td>
<td>0.76</td>
<td>6.53</td>
<td>0.88</td>
<td>0.50</td>
<td>0.52</td>
<td>0.49</td>
</tr>
</tbody>
</table>
TABLE 4. Confusion matrix for downy mildew estimation in three severity classes using the crisp and the fuzzy thresholds (with the sigmoid membership function) for Sets 1 and 2. The percentage of the discs from the true class (based on the expert visual assessment) represented in the prediction is included next to the number of discs. A summary of the discs correctly classified is included in the last column.

<table>
<thead>
<tr>
<th>Dataset</th>
<th>Threshold type</th>
<th>True class based on visual assessment</th>
<th>Discs by class</th>
<th>Predicted class</th>
<th>Discs correctly classified</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Low</td>
<td>30</td>
<td>Low</td>
<td>27 (90 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Middle</td>
<td>34</td>
<td>Middle</td>
<td>1 (3 %)</td>
</tr>
<tr>
<td>Set-1</td>
<td>Sigmoidal (58-119)</td>
<td>High</td>
<td>45</td>
<td>High</td>
<td>3 (7 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Low</td>
<td>30</td>
<td>Low</td>
<td>27 (90 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Middle</td>
<td>34</td>
<td>Middle</td>
<td>1 (3 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High</td>
<td>45</td>
<td>High</td>
<td>2 (4 %)</td>
</tr>
<tr>
<td></td>
<td>Crisp (89)</td>
<td>Low</td>
<td>214</td>
<td>Low</td>
<td>211 (99 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Middle</td>
<td>39</td>
<td>Middle</td>
<td>21 (54 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High</td>
<td>8</td>
<td>High</td>
<td>2 (25 %)</td>
</tr>
<tr>
<td>Set-2</td>
<td>Sigmoidal (58-119)</td>
<td>Low</td>
<td>214</td>
<td>Low</td>
<td>210 (98 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Middle</td>
<td>39</td>
<td>Middle</td>
<td>20 (51 %)</td>
</tr>
<tr>
<td></td>
<td></td>
<td>High</td>
<td>8</td>
<td>High</td>
<td>2 (25 %)</td>
</tr>
</tbody>
</table>

Overall, the obtained results seem to indicate that the method developed offers improved performance in regression and classification using the fuzzy threshold, which allows yielding a quantitative estimation of the severity of infection close to that of the experts.

Considering the best performing thresholds in regression and classification and their equivalent crisp thresholds, the two different datasets were analysed individually (Tables 3 and 4). Table 3 shows the individual regression and classification results, displaying a large difference between the two datasets, especially in the classification results. Set-1 showed high levels of classification accuracy (77–83 %), while Set-2 was characterised by a high level of accuracy (88–89 %) but low F1 score, precision and recall scores (close to 0.50, Table 3). The number of discs correctly classified or classified as other levels can be seen in detail in Table 4, along with the confusion matrices associated with the methods that used the best performing thresholds (results split by datasets). In Set-1, the infection levels are correctly classified in most cases, in contrast to Set-2, where the classification is notable for the correct classification of the low severity level (correctly classifying 99 %), with most medium severity discs being classified as having low severity (51–54 %) and 75 % of high severity discs being classified as having medium severity. This occurs as the variability of the data was low, and the classification focused on lower severities due to this imbalance. As can be seen in Figure 6a,b, Set-1 contained severities varying between 0 and 100, making its estimation results more representative.

This new method has been developed using two large and different datasets: Leaves from two grapevine varieties and with image acquisition carried out under different indoor conditions (operators, artificial illumination and digital cameras). The new method was validated by expert visual assessment, as eleven trained experts evaluated each leaf disc from both datasets using a reference method in plant pathology. The strong relation between the expert visual assessments and the downy mildew severity computed by the algorithm suggests that fuzzy logic could assist adequately for automated disease evaluation very close to expert human assessment.

The developed method could be applied in numerous studies for the phenotypization of *P. viticola* traits, such as fungicide resistance and fitness (Corio-Costet et al., 2011; Massi et al., 2021; Toffolatti et al., 2015) or the evaluation of pathogen resistance in grapevine (Bellin et al., 2009; Possamai et al., 2020; Toffolatti et al., 2012) and efficacy of antifungal compounds (Colombo et al., 2020). The performance of the method could be improved in the future by trying to solve the errors due to the detection of nerves in the leaves, water droplets or light reflections by performing a segmentation with deep learning, which has been shown to have a high accuracy in similar problems (Lin et al., 2019). The effective application of deep learning requires a large and varied dataset (Barbedo, 2018a, 2018b), so to perform this type of segmentation and avoid overfitting more varied images of leaf discs would be needed, using different illumination, leaf discs with different sizes, different grapevine varieties, and, especially, leaf discs with severity percentages between 0 and 100 % and avoiding an imbalance of severity levels.

The main advantages of the new method are the following: Objective, quantifiable, rapid, automated and trained personnel is not required. The outcomes of this work agree with previous studies in demonstrating that the use of RGB
images with computer vision techniques for the estimation of disease severity in plants provides advantages over expert estimation (Mukherjee, 2020; Nagi and Tripathy, 2020; Peressotti et al., 2011) as the latter involves some degree of subjectivity and require trained experts. In the same way, RGB and computer vision approaches could be preferred over the utilisation of other types of images, such as hyperspectral images (Bock et al., 2020), due to the lower cost of equipment and operator expertise required in the former, as well as the speed with which information is obtained from the plant images once the method is developed (Bock et al., 2020). With our new method, it is possible to estimate the disease severity of 6131 discs per hour, as opposed to manual assessment, where each trained expert assesses approximately 185 discs per hour. This implies an improvement in time compared to the expert evaluation, which, together with the objectivity that allows having the same method to analyse all leaf discs, and the automation of the evaluation, achieves an accurate and useful method for the evaluation of downy mildew in grapevine leaves.

This new method can be applied to other crops and plant diseases in agriculture, collecting leaves from the field and taking images with a digital camera under indoor conditions with artificial illumination. Fuzzy logic could help to treat differently the colours of the spots that represent the symptoms in grapevine leaves. Recently, Gutiérrez et al. (2021) used computer vision and deep learning to differentiate downy mildew and other pests using images taken under day-light conditions in commercial vineyards. These results suggest that the developed method can be applied to leaf images taken in both field and laboratory conditions.

In this work, computer vision and fuzzy logic techniques have enabled the estimation of the severity of downy mildew in the leaves of different grapevine varieties under laboratory conditions with high performance, automatically and objectively. Fuzzy logic has been commonly used in agricultural applications (when compared to other computer vision and machine learning approaches), but these results point out that it can be a powerful tool either as a core component or included in a larger automated identification system, opening several ways of applying fuzzy logic to more agricultural-themed solutions involving computing or electronics. The next steps would involve the adaptation of this method to be applied in the estimation of downy mildew or other fungal diseases, such as powdery mildew or botrytis, in field conditions, grapevines or in other crops. Improved monitoring of crop disease incidence at early stages would contribute to better tracking the infection and actively reacting (either through spraying or another strategy) in a more optimised way.

**CONCLUSIONS**

A new method, based on the combined application of computer vision and fuzzy logic, has been developed and validated for the automated evaluation of downy mildew severity in grapevine leaves. Fuzzy logic contributed to the assessment of disease severity according to sporulation intensities and provided a detailed visualisation of the different sporulation intensities. The estimation of downy mildew severity provided by this new method was strongly related to the visual assessment of the infection percentage rated by eleven trained experts. However, the new method was objective, cheap and fast enough to be automated and serve as decision support in the control of fungal crop diseases, such as downy mildew.

The developed method demonstrated its effectiveness with images of different grapevine varieties taken under different conditions, achieving an estimate of downy mildew severity similar to that provided by experts. This demonstrates the robustness of the method, based on fuzzy logic, and its possible application to other grapevine diseases or its adaptation to analyse leaves collected in the field.

**ACKNOWLEDGEMENTS**

This work has been developed as part of the project NoPest (Novel Pesticides for a Sustainable Agriculture), which received funding from the European Union Horizon 2020 FET Open program under Grant agreement ID 828940. It was also supported by the Spanish Ministry of Economy and Competitiveness under Grant PID2020-119478GB-I00. Inés Hernández would like to acknowledge the research funding FPI grant 1150/2020 by Universidad de La Rioja and Gobierno de La Rioja.

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